

## Numerik 2 – Übung06 – Georg Kuschk

1.a)

$$\begin{aligned}
 s_f(x_i) &= f(x_i) \\
 s_f(x) &= a_0 + b_0(x - x_i) \quad \text{für } x \in [x_i, x_{i+1}] \\
 \Rightarrow a_0 &= f(x_i) \\
 \Rightarrow b_0 &= \frac{f(x_{i+1}) - f(x_i)}{x_{i+1} - x_i} \\
 \Rightarrow s_f(x) &= f(x_i) + \frac{f(x_{i+1}) - f(x_i)}{x_{i+1} - x_i}(x - x_i)
 \end{aligned}$$

1.b)

$$\begin{aligned}
 \|g'\|_2^2 &= \int_a^b (g')^2 dx = \int_a^b (s_f' + (g' - s_f'))^2 dx \\
 &= \int_a^b (s_f')^2 dx + \underbrace{2 \int_a^b s_f' (g' - s_f') dx}_{\text{zu zeigen: } =0} + \underbrace{\int_a^b (g' - s_f')^2 dx}_{\geq 0} \\
 &\geq \int_a^b (s_f')^2 dx = \|s_f'\|_2^2
 \end{aligned}$$

zu zeigen :

$$\begin{aligned}
 \int_a^b s_f' (g' - s_f') dx &= \sum_{i=0}^{n-1} \int_{x_i}^{x_{i+1}} s_f' (g' - s_f') dx = \sum_{i=0}^{n-1} \left( [s_f'(g - s_f)]_{x_i}^{x_{i+1}} - \int_{x_i}^{x_{i+1}} s_f'' (g - s_f) dx \right) \\
 &= \sum_{i=0}^{n-1} \left( s_f'(x_{i+1}) \cdot \underbrace{(g(x_{i+1}) - s_f(x_{i+1}))}_{=0} - s_f'(x_i) \cdot \underbrace{(g(x_i) - s_f(x_i))}_{=0} - \int_{x_i}^{x_{i+1}} \underbrace{s_f''(g - s_f)}_{=0} dx \right) \\
 &= 0 \\
 \Rightarrow \|g'\|_2 &\geq \|s_f'\|_2
 \end{aligned}$$

1.c)

$$\begin{aligned}
 \|g'\|_2^2 &\geq \|s_f'\|_2^2 = \int_a^b (s_f')^2 dx = \sum_{i=0}^{n-1} \int_{x_i}^{x_{i+1}} (s_f')^2 dx = \sum_{i=0}^{n-1} \int_{x_i}^{x_{i+1}} \left( \frac{f(x_{i+1}) - f(x_i)}{x_{i+1} - x_i} \right)^2 dx \\
 &= \sum_{i=0}^{n-1} \int_{x_i}^{x_{i+1}} \frac{(f(x_{i+1}) - f(x_i))^2}{x_{i+1} - x_i} dx = \sum_{i=0}^{n-1} \frac{(g(x_{i+1}) - g(x_i))^2}{x_{i+1} - x_i}
 \end{aligned}$$

2.)

$i=1$ :

$$\frac{h_0}{6}c_0 + \frac{h_0+h_1}{3}c_1 + \frac{h_1}{6}c_2 = f \dots \\ c_0 = S_{\Delta}''(a) = S_{\Delta}''(b) = c_{l+1}$$

$i=l+1$ :

$$\frac{h_l}{6}c_l + \frac{h_l+h_{l+1}}{3}c_{l+1} + \frac{h_{l+1}}{6}c_{l+2} = f \dots$$

$$c_{l+2} = c_1$$

$$h_{l+1} = h_0$$

$$f_{l+2} = f_1$$

$\Rightarrow$

$$\begin{pmatrix} \frac{h_0+h_1}{3} & \frac{h_1}{6} & 0 & \cdots & \frac{h_0}{6} \\ \frac{h_1}{6} & \frac{h_1+h_2}{3} & \frac{h_2}{6} & & \\ 0 & \ddots & \ddots & \ddots & \\ \vdots & & & & \\ \frac{h_0}{6} & & \frac{h_{l-1}}{6} & \frac{h_{l-1}+h_l}{3} & \frac{h_l}{6} \\ & & & \frac{h_l}{6} & \frac{h_l+h_0}{3} \end{pmatrix} \cdot \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_{l+1} \end{pmatrix} = \begin{pmatrix} \frac{f_2-f_1}{h_1} - \frac{f_1-f_0}{h_0} \\ \vdots \\ \frac{f_1-f_0}{h_0} - \frac{f_{l+1}-f_l}{h_l} \end{pmatrix}$$

$\Rightarrow$

$$c_0 = \frac{23}{4}, \quad c_1 = -\frac{7}{4}, \quad c_2 = \frac{7}{8}, \quad c_3 = -\frac{13}{4}$$

$$i=0: [0,1] : s_0(t) = -\frac{15}{24}t + \frac{23}{8}t^2 - \frac{15}{12}t^3$$

$$i=1: [1,3] : s_1(t) = 1 + \frac{11}{8}(t-1) - \frac{7}{8}(t-1)^2 + \frac{11}{6 \cdot 16}(t-1)^3$$

$$i=2: [3,5] : s_2(t) = 2 + \frac{1}{2}(t-3) + \frac{7}{16}(t-3)^2 - \frac{33}{6 \cdot 16}(t-3)^3$$

$$i=3: [5,6] : s_3(t) = 2 - \frac{15}{8}(t-5) + \frac{13}{8}(t-5)^2 + \frac{5}{6}(t-5)^3$$

**3.a)**

Randbedingung:  $f_0 = f_n = 0$

$\Rightarrow s'$  hat eine Nullstelle in  $(t_0, t_n)$  - (Satz von Rolle)

Randbedingung:  $s'(t_0) = 0$ ,  $s'(t_n) = 0$

$\Rightarrow s''$  hat zwei getrennte Nullstellen in  $(t_0, t_n)$

$s''$  ist stückweise linear durch  $(t_0, 0), (t_1, c_1), \dots, (t_l, c_l), (t_{l+1}, 0)$

$\Rightarrow c_1 = 0, c_2 = 0$  für  $l = 2$

und  $c_1 = 0$  für  $l = 1$

**3.b)**

$t = 0, l = 3$  :

$$s(t_0) = s(t_2) = s(t_4)$$

$\Rightarrow s'$  hat Nullstellen  $t_0, t_4$  in  $(t_0, t_2)$  und  $(t_2, t_4)$

$\Rightarrow s''$  hat 5 getrennte Nullstellen, stückweise linear  $\Rightarrow s'' \equiv 0 \Rightarrow s \equiv 0$

**3.c)**

$$t_i := -2, -1, 0, 1, 2$$

$$f := 1$$

linke Randbedingung:

$$a_0 = b_0 = c_0 = 0, d_0 \text{ frei}$$

$$\Rightarrow s(t_1) = \frac{1}{6}d_0, \quad s'(t_1) = \frac{1}{2}d_0, \quad s''(t_1) = d_0$$

rechte Randbedingung:

$$d_3 \text{ frei}$$

$$c_3 = -d_3$$

$$b_3 = \frac{1}{2}d_3$$

$$a_3 = -\frac{1}{6}d_3$$

$$f = 2 \Rightarrow a_2 = 2$$

Stetigkeitsbedingungen in  $t = 0$  :

$$a_1 + b_1 + \frac{1}{2}c_1 + \frac{1}{6}d_1 = a_2$$

$$b_1 + c_1 + \frac{1}{2}d_1 = b_2$$

$$c_1 + d_1 = c_2$$

Stetigkeitsbedingungen in  $t = 1$  :

$$a_2 + b_2 + \frac{1}{2}c_2 + \frac{1}{6}d_2 = a_3$$

$$b_2 + c_2 + \frac{1}{2}d_2 = b_3$$

$$c_2 + d_2 = d_3$$

$\Rightarrow$  Unbekannte  $d_0, d_1, d_2, d_3, b_2, c_2$  und 6 Gleichungen

$\Rightarrow$

$$d_0 = \frac{3}{2}, \quad d_1 = -\frac{9}{2}, \quad d_2 = \frac{9}{2}, \quad d_3 = -\frac{3}{2}$$

$$a_1 = \frac{1}{4}, \quad a_3 = \frac{1}{4}, \quad b_1 = \frac{3}{4}, \quad b_2 = 0, \quad b_3 = -\frac{3}{4}$$

$$c_1 = \frac{3}{2}, \quad c_2 = -3, \quad c_3 = \frac{3}{2}$$